Quiz

In Harris corner detector: If the Eigen values are large, it means that these image points represent a flat region \*

1/1

True

Flase

Feature indexing means that creating feature vectors using the detected features \*

0/1

True

Flase

An expressive texture is represented at the point with high boundary intensity changes \*

1/1

True

Flase

Good fusion is mandatory for good registration \*

0/1

True

Flase

Good feature representation methods should be robust against illumination changes and noise but not necessarily against geometric transformations \*

0/1

True

Flase

Corners are the most strong interest points \*

1/1

True

Flase

Multitemporal registration means overlaying images taken at different times or view points \*

0/1

True

Flase

The aperture problem happens usually at edges and flat regions \*

1/1

True

Flase

الاسم كاملا باللغة العربية: \*

كيرلس هاني وديع

Features like points and corners are extracted from regions of interest within the image \*

1/1

True

Flase

Corner detection approaches can be either brightness based or boundary based \*

1/1

True

Flase

Keypoints are another name for interest points or local points in regions of interest \*

1/1

True

Flase

Radar images are created using active sensing that uses sun's energy \*

1/1

True

Flase

Edges and corners are classified as global features \*

1/1

True

Flase

Outliers represent the true matches of interest points \*

1/1

True

Flase

Optical and radar images have the same characteristics \*

1/1

True

Flase